[Posynomial] Geometric Programming

The general primal problem of geometric programming (GP) [Duffin et al.] is to

Minimize
$$g_0(x)$$

subject to $g_i(x) \le 1$, i=1, 2, ..., m
 $x > 0$ (1)

where the functions gi are posynomials, i.e.,

$$g_{i}(x) = \sum_{j=1}^{T_{i}} c_{ij} \prod_{n=1}^{N} x_{n}^{a_{ijn}}$$
(2)

The exponents a_{ijn} are arbitrary real numbers, but the coefficients c_{ij} are assumed to be positive constants and the decision variables x_n are required to be strictly positive. The corresponding posynomial GP dual problem is to

Maximize
$$v(\delta, \lambda) = \prod_{i=0}^{m} \prod_{j=1}^{T_i} \left(\frac{c_{ij}\lambda_i}{\delta_{ij}} \right)^{\delta_{ij}}$$
 (3)

subject to
$$\sum_{i=0}^{m} \sum_{j=1}^{T_i} a_{ijn} \delta_{ij} = 0, n=1, 2, ..., N$$
 (4)

$$\lambda_{i} = \sum_{j=1}^{T_{i}} \delta_{ij}, i=0, 2, ..., m$$
(5)

$$\lambda_0 = 1 \tag{6}$$

$$\delta_{ij} \ge 0, \ \neq 1, 2, ..., T_i, \ i=0, 1, ..., m$$
(7)

This dual problem offers several computational advantages: after using (5) to eliminate λ , the logarithm of the objective (3) is a concave function to be maximized over a linear system. This linear system has T variables, where $T=T_0 + T_1 + ... + T_m$, and N+1 equations, and hence T-(N+1) is referred to as its *degree of difficulty*. If an optimal dual solution (δ^*, λ^*) is known, then the following relationships may be used to compute a primal solution x* in nonpathological cases:

$$\delta_{ij}^* g_i(x^*) = \lambda_i^* c_{ij} \prod_{n=1}^N x^* a_{ijn}^{a_{ijn}}, j=1, 2, ..., T_i, i=0, 1, ..., m$$
(8)

where $g_0(x^*)=v(\delta^*,\lambda^*)$ and, for i > 0, $g_i(x^*)=1$ if $\lambda_i \ge 0$. Note that, from these relationships, one may obtain a system of equations linear in the logarithms of the optimal values of the primal variables:

$$\sum_{n=1}^{N} a_{ijn} \ln x_n = \ln \left(\frac{\delta_{ij}^* g_i(x^*)}{\lambda_i^* c_{ij}} \right), \quad j=1, 2, ..., T_j \text{ for each } i=0, 1, ..., m \text{ such that } \lambda_i^* \neq 0_{(9)}$$

Typically, but not always, the system of linear equations (9) uniquely determines the optimal x^* . (Cf. [Dembo] for a discussion of the recovery of primal solutions from the dual solution in general.)

References

- Boyd, S., Kim, S.-J., Vandenberghe, L., & Hassibi, A. (2007). "A tutorial on geometric programming". *Optimization and Engineering*, 8(1), 67-127.
- Dembo, R. S. (1980). "Dual to Primal Conversion in Geometric Programming". In M. Avriel (Eds.), Advances in Geometric Programming (pp. 333-342). New York: Plenum Press.
- Duffin, R. J., E. L. Peterson, and C. M. Zener (1967). *Geometric Programming*. New York, John Wiley and Sons.